

## EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L17	371	(702/151).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/05/15 13:45
L18	0	(sensor and angular and solid and orientation and random and confrontation).clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/15 13:46
L19	2	(sensor and angular and solid and orientation and random).clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/15 13:46
L20	4	(sensor and angular and solid and random).clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/15 13:46

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Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L8	18	(US-20020111762-\$ or US-20020188416-\$ or US-20020153451-\$).did. or (US-6829558-\$ or US-6931323-\$ or US-5255442-\$ or US-5526022-\$ or US-5645077-\$ or US-6487516-\$ or US-6889934-\$ or US-5953683-\$ or US-6543146-\$ or US-6208936-\$ or US-5682317-\$ or US-5179525-\$ or US-6611783-\$ or US-6421622-\$ or US-6636826-\$).did.	US-PGPUB; USPAT	OR	ON	2007/05/15 12:21
L10	9	l8 and ((guess estimate estimated random randomly) same (position orientation angle angular))	US-PGPUB; USPAT	OR	ON	2007/05/15 12:21
L11	8	(angular same sensor) and (random near3 (seed guess))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/15 13:22
L12	367	(angular same sensor) and ((repeat repeated iterative iteratively) same (threshold predetermined less) same difference)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/15 13:23
L13	200	l12 and (gravity magnetic)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/15 13:23
L14	46	l13 and accelerometer	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/15 13:24
L15	42	l14 and (initial estimate random seed)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/15 13:24

## EAST Search History

L16	24	I15 and @ad < "20020405"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/15 13:24
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